New PETRA III Concept

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- Weak points of our "old" control system
- Our concept
 - □ The hardware
 - building groups
 - building modules
 - using software modules
 - □ The interlock
 - software interlock
 - hardwired interlock

outlook

- lots of cables
- Documentation of cables & electronics is bad or not "Up to date"
- many different components
- interlock and control electronic is hardwired (inflexibility)
- only simple interlock-logic (difficult to build "machine-dependent " interlock)
- multiplicity of on signal (analog signal distribution causes calibration errors)
- not every signal is archived
- external Transient recorder (need to be plugged, usually not enough channels)
- PLC needs special modules for special sensors (PT100, analog in, analog out, Stepper motor) and can't acquire fast ADC- signals
- Expert- knowledge for troubleshooting & repair is needed

Expert knowledge



Many people can repair a Computer without knowing something about electronics or IT.

They change components.

Wouldn't it be nice to have this at a transmitter too ???

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Difference between PC and Transmitter:

Transmitter is complex

=> split Transmitter into parts (functional groups)

functional group represents PC from previous slice

=> split functional group into modules

module represents e.g. sound card

=> module has a clear task (e.g. conditioning signals)



Functional groups



- a functional group fits in one rack
- main cabling is done within one functional group
- no cables are longer than 3 to 4 m
- You can follow a cable by "hand"
- cabling between the groups are reduced to 5 to 6 cables



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Moduls



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ELWIS- modules can monitor and drive all kind of inputs / outputs incl. Rf- or fast DC- signals

These components are in more or less every functional group





ELWIS modules

- Monitoring and acting all kind of inputs / outputs incl. Rf- or fast DC- signals with one set of modules
- one signal is only once converted and can be distributed anywhere
- signal is in the network and is archived
- every fast signals are additional "transient recorded"
- Same signal for interlock, monitoring and Transientrecorder (same calibration)
- The software for acquiring and interlocking is the same in every functional group (**building software modules**)

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Interlocking:

- Main interlocking by software
- and via Ethernet
- flexible programming possible



Combination of Interlock Conditions

Klystron Crowbar System:

3 sensors instead of one at least 2 of 3 have to detect an overcurrent

RF Load Interlock:

∆T AND rf-power must exceed the threshold not only

Klystron Focus Interlock:

supply current AND supply voltage must fail not 021

But:

Essential interlocks are hardwired

(never trust software !?!)



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Outlook

- most functional groups are (more or less) programmed
- basic software modules are identical in each group
- software interlock tested, but response time is about 0.5 s
- cavity self calibration (Phase & symmetry) is possible
- intermediate communication has to be programmed / tested
- goal is a power on test for the whole transmitter and a "on demand" self calibration