

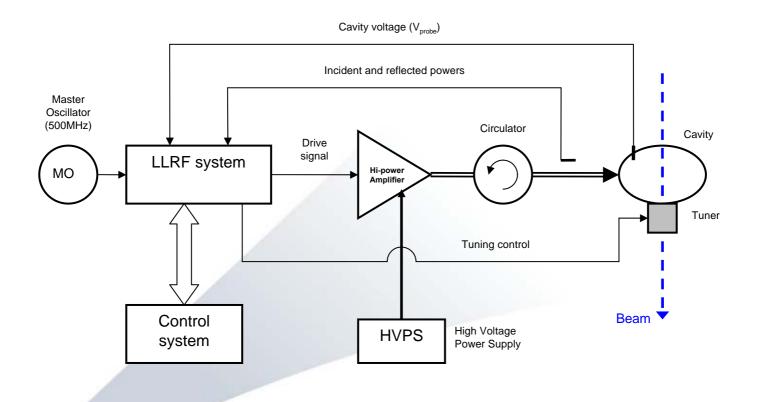
# Low Level RF of ALBA

## (A preliminary study)

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# **General view of the RF system**



The task of the LLRF is the regulation of the amplitude, frequency and phase of the RF wave.



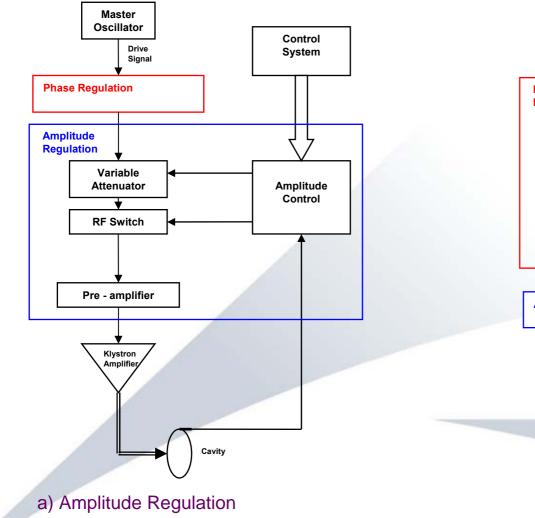


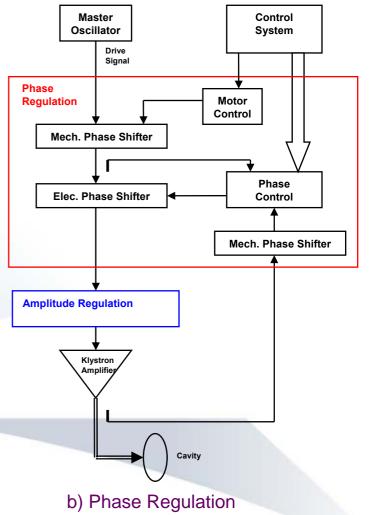
## LLRF - hardware

- □ Sensors for the incident, reflected and cavity power (P<sub>inc</sub>, P<sub>refl</sub>, P<sub>probe</sub>)
- The required hardware for the isolation and amplification of the RF signals
- The required Digital / Analog circuits for regulation, interfacing, ADC, DAC, signal processing, etc.
- □ Drive power amplifier
- **PIN diode**
- Master oscillator
- □ Other modules including auxiliary power supplies, PLL, Interlock, etc.



# **Amplitude and phase regulation loops**







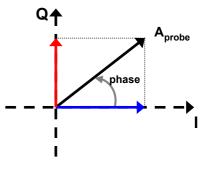


# **I-Q demodulator and rotation matrix**

**Demodulation:** 

 $V(t) = I.Cos(\omega t) + Q.Sin(\omega t)$ 

$$\begin{cases} I = A_{probe} \times Cos(\varphi_{probe} - \varphi_{MO}) \\ Q = A_{probe} \times Sin(\varphi_{probe} - \varphi_{MO}) \end{cases}$$



## **Modulation:**

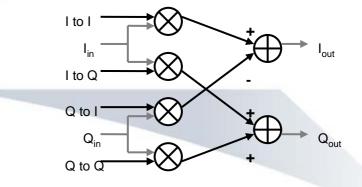
$$A_{probe} = \sqrt{I^2 + Q^2}$$
  $\varphi_{probe} - \varphi_{MO} = \arctan$ 

$$\varphi_{probe} - \varphi_{MO} = \arctan 2(\frac{Q}{I})$$

 $\sim 1$ 

## **Rotation matrix:**

$$\begin{bmatrix} I_{out} \\ Q_{out} \end{bmatrix} = A \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \times \begin{bmatrix} I_{in} \\ Q_{in} \end{bmatrix}$$



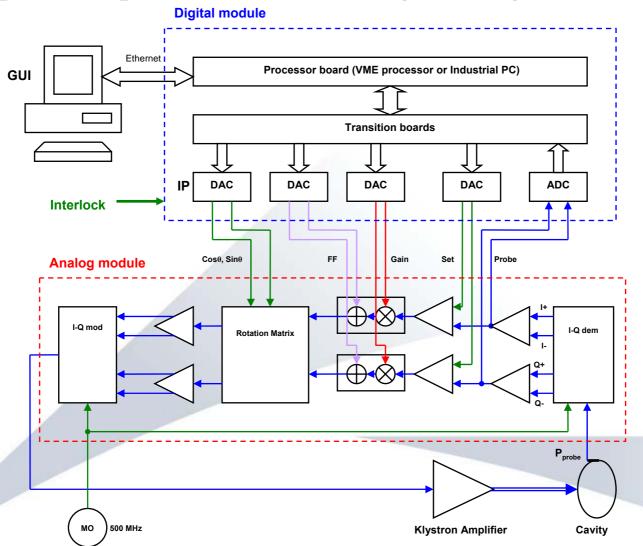


## **General suggestions for ALBA LLRF**

- I-Q demodulation is more favourable, because two identical regulators will be used acting on baseband signals with wider phase control range compared to the traditional amplitudephase loops.
- It's more desirable to use digital electronics which provides more flexibility, possibility of future changes by the software, better diagnostics and higher functionality compared to analog electronics.



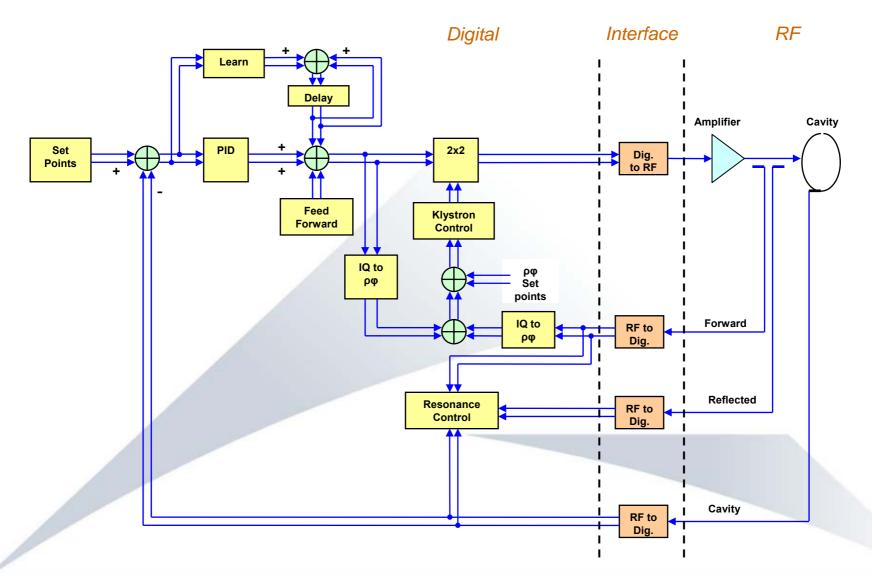
## **Amplitude / phase control (analog and digital)**



LLRF of ALBA

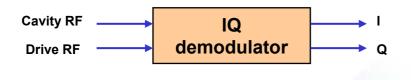
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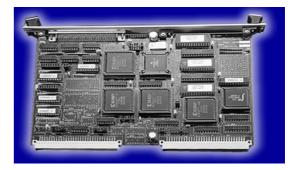
# **Amplitude / phase control (all digital)**





# **Tuner control**





## **Cavity tuner control:**

- An IQ demodulator detects the phase difference between the drive RF and the actual cavity voltage
- The LLRF system drives the phase using the relation Arctan(Q/I)
- The LLRF drives the cavity to maintain the desired phase difference





## **Inputs / Outputs for LLRF controls**

### Cavity voltage control inputs:

- 1. Reference RF
- 2. Cavity Voltage
- 3. Cavity In-phase setpoint (FB)
- 4. Cavity Quadrature setpoint (FB)
- 5. IQ regulator gains
- 6. Cavity In-phase setpoint (FF)
- 7. Cavity Quadrature setpoint (FF)
- 8. Rotation matrix parameters

### Cavity voltage control outputs:

- 1. Power amplifier drive
- 2. Cavity voltage In-phase monitor
- 3. Cavity voltage Quadrature monitor

## Cavity tuner control inputs:

- 1. Cavity voltage
- 2. Derive RF

### Cavity tuner control outputs:

- 1. Cavity tuning In-phase (I)
- 2. Cavity tuning Quadrature (Q)

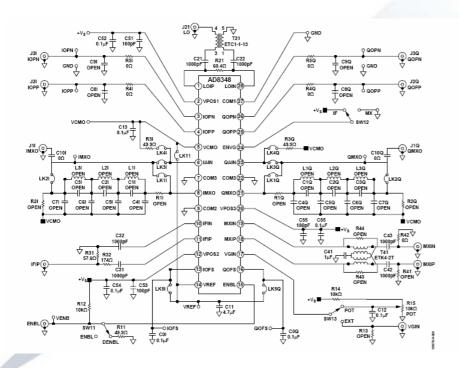
Electrical and performance specifications of the Input / Output signals still have to be defined.





## **The first step – IQ demodulator**

- > We'll need it with both Digital and Analog Reg.
- Detailed design is available
- Comparably easy to build
- Can be tested with a function generator





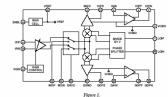
#### 50 MHz–1000 MHz Quadrature Demodulator

#### AD8348

#### FEATURES

Integrated I/Q demodulator with IF VGA amplifie Operating IF frequency 50 MHz to 1000 MHz  $(3 \text{ dB IF BW of } 500 \text{ MHz driven from } R_s = 200 \Omega)$ Demodulation bandwidth 75 MHz Linear-in-dB AGC range 44 dB Third order intercept IIP3 +28 dBm @ min gain (FIF = 380 MHz) IIP 3 – 8 dBm @ max gain (F<sub>IF</sub> = 380 MHz) Quadrature demodulation accuracy Phase accuracy 0.5° Amplitude balance 0.25 dB Noise figure 11 dB @ max gain (Fr = 380 MHz) LO input -10 dBm Single supply 2.7 V to 5.5 V Power-down mode Compact 28-lead TSSOP package

APPLICATIONS QAM/QPSK demodulator W-CDMA/CDMA/GSM/NADC Wireless local loop LMDS FUNCTIONAL BLOCK DIAGRAM



Optionally, the IF VGA can be disabled and bypassed. In this mode, the IF signal is applied directly to the quadrature mixer inputs via the MXIP and MXIN pins.

Separate I and Q channel baseband amplifiers follow the baseband outputs of the mixers. The voltage applied to the VCMO pin sets the dc common-mode voltage level at the baseband outputs. Typically VCMO is connected to the internal VREF voltage, but it can also be connected to an external voltage. This flexibility allows the user to maximize the input dynamic range to the ADC. Connecting a bypass capacitor at each offset compensation inrunt (IOES and ODES) nulls dc offsets ronduced in





## The next steps

- 1. I-Q demodulator (A/D3343 from A/nalog Devices)
  - Can be designed and made at CELLS
  - Test with a function generator
- 2. Other parts of the "Analog module"
- 3. ADC, DAC and processor boards ("Digital Module")
  - Off the shelf, but still need programming
  - will be done in collaboration with the Control Group
- 4. Test with simulated system
- 5. Interfacing with the control system and GUI
  - Will be done mainly by the Control Group
- 6. Commissioning and trouble-shooting